

Techniques and results concerning relationships between modal \exists -logics

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Validity of a modal formula on a Kripke frame is defined as the global truth under any valuation of propositional variables. Similarly we can consider existential validity: a formula A is existentially valid on a frame \mathcal{F} if it is satisfiable under any valuation. That is, for any valuation, there is a world satisfying A . Collection of formulas existentially valid on a class of frames is called the \exists -logic of the respective class. The \exists -logic corresponding to the class of all frames was determined by Humberstone [3], and Zolin [7] posed the question of axiomatizability of \exists -logics corresponding to other classes of frames.

It is known (a result of Tiomkin and Kaminski [6]) that \exists -logics of $S4$ -frames and $S5$ -frames coincide. The technique used to prove this result can also be used to prove many other similar results. This includes, as we will show, everything that holds between the \exists -logics of the classes of frames corresponding to the fifteen traditional logics [2] (K extended with a subset of $\{B, D, T, 4, 5\}$). The essential requirement for applicability of the method is for a logic to have the so-called global finite model property [4], [5], [1].

References

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